## **V2406C Windows Software User's Manual**

Version 1.2, January 2022

www.moxa.com/product



### V2406C Windows Software User's Manual

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# **System Initialization**

In this chapter, we describe how to initialize the system settings on the V2406C computer when you boot up the computer for the first time. When you turn on the computer, you will see the Windows Out of Box Experience (OOBE) wizard. OOBE consists of a series of screens that require customers to accept the license agreement, connect to the internet, log in with, or sign up for a Microsoft Account, and share information with the OEM.

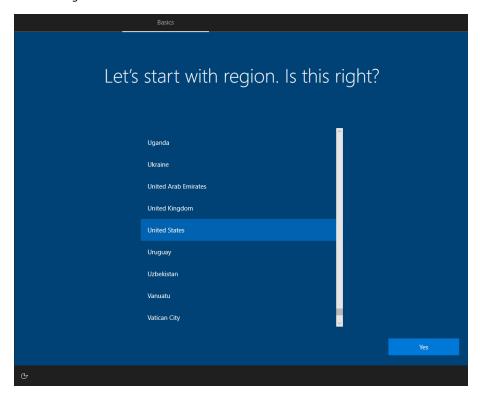
The following topics are covered in this chapter:

- ☐ Initializing User Settings
- ☐ Initializing the System

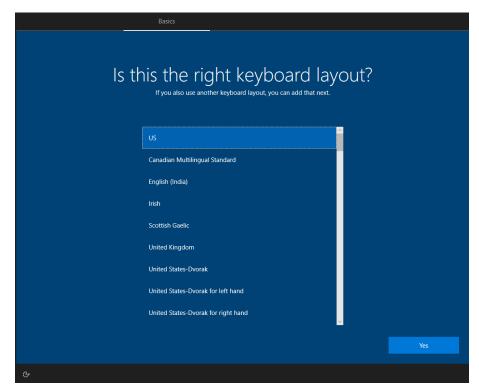
## **Initializing User Settings**

The following is a non-exhaustive list of OOBE screens that you will see in the order that they are listed here:

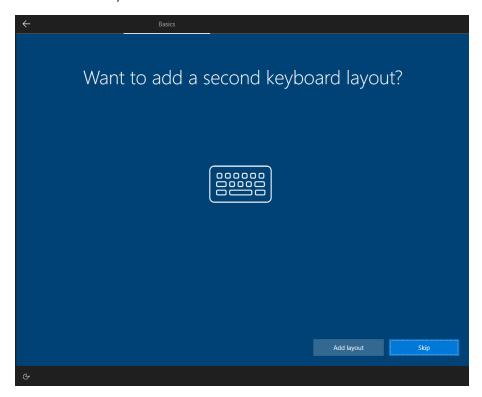
1. Select a region.



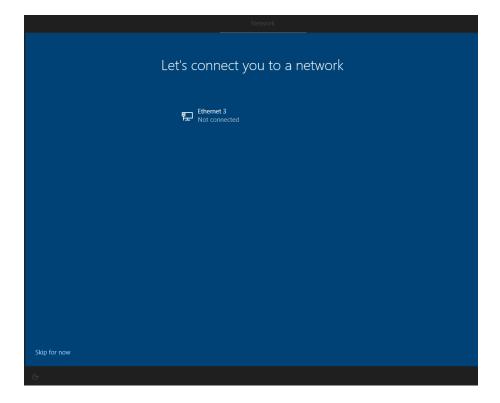
2. Select a keyboard.

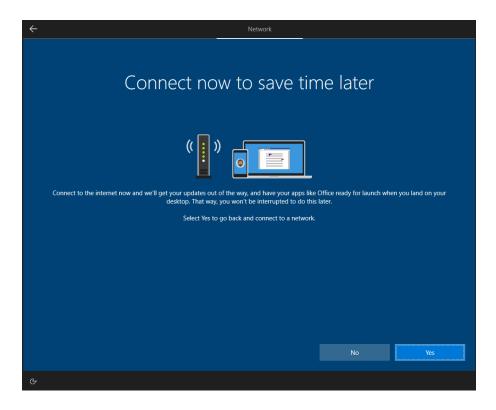


3. Select a second keyboard.

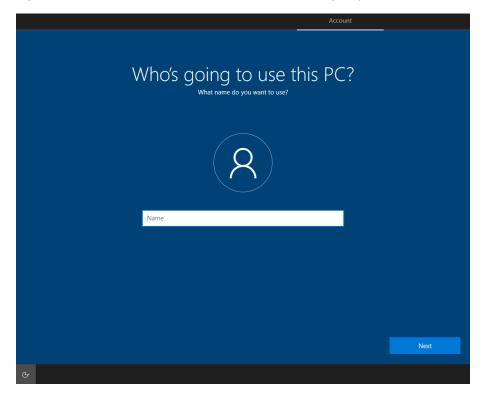


4. Connect to a network.

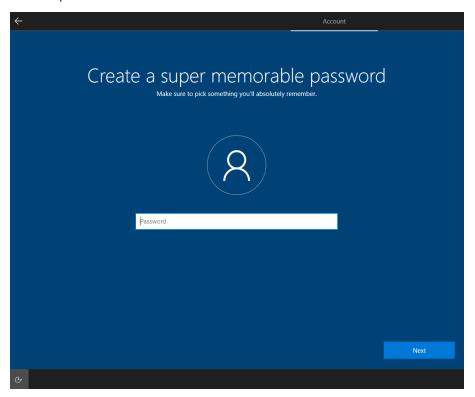




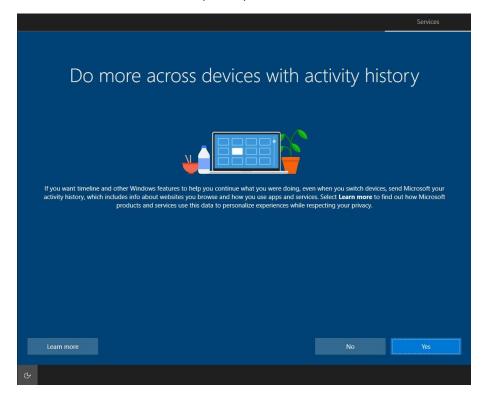
5. Sign in to or create a local account or a Microsoft account (MSA).



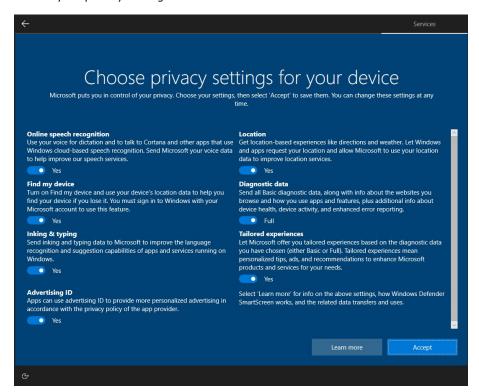
6. Create a password.



7. Do more across device with activity history.

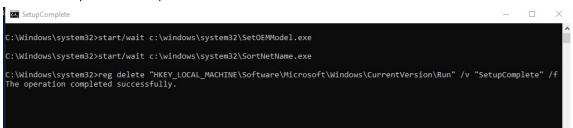


8. Choose your privacy settings.



### **Initializing the System**

- 1. After the OOBE settings, you will be redirected to the device desktop of the device.
- 2. Wait until the process is complete.



After the process is completed, the system initialization is done. The device will reboot, and the new settings will take effect after the system restarts.

# **B**it**L**ocker

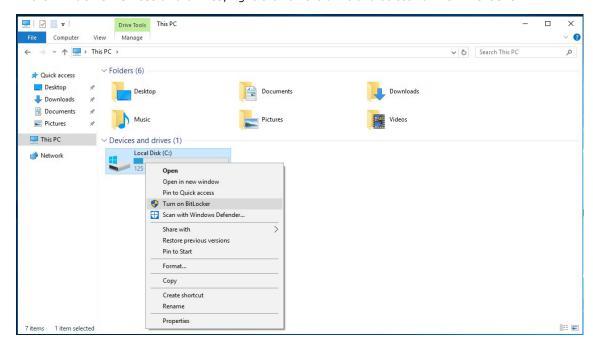
This chapter describes the BitLocker setup process.

The following topics are covered in this chapter:

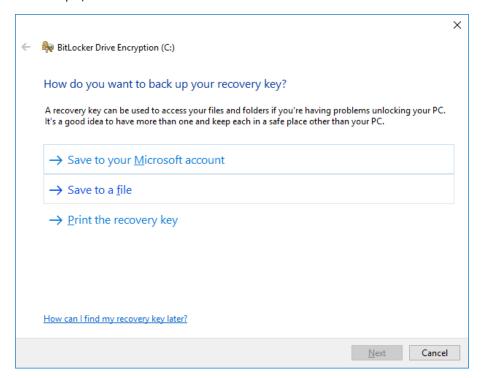
- ☐ Enabling the BitLocker
- □ Disabling the BitLocker

## **Enabling the BitLocker**

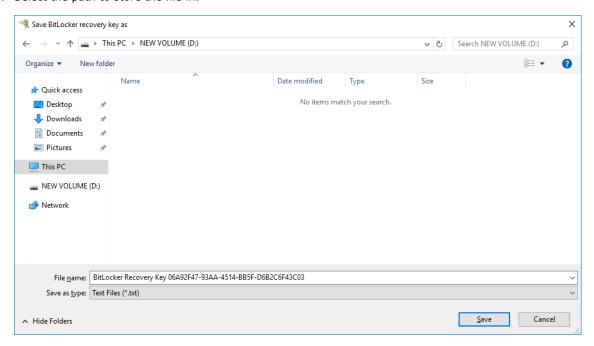
1. In the Windows Devices and drives, right-click on the drive and select Turn on BitLocker.



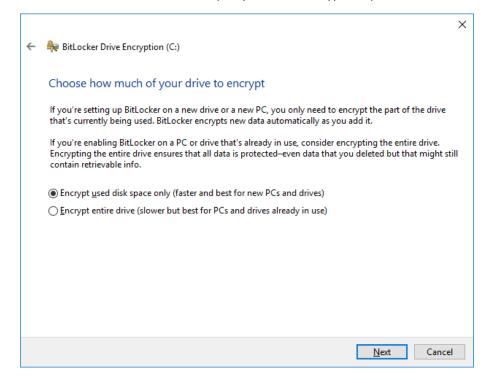
2. Select an option to back up the recovery key. For example, select **Save to a file**.



3. Select the path to store the file in.

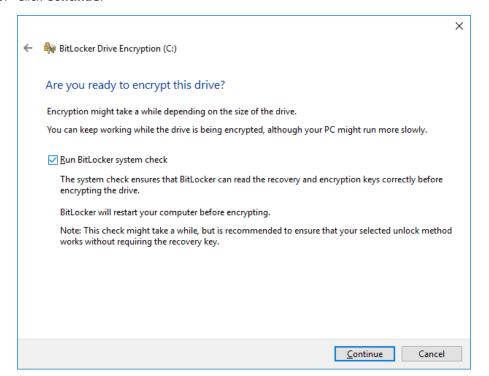


4. Follow the onscreen instructions to specify the drive encryption options.

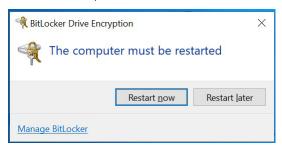




### 5. Click Continue.



6. Restart the computer.

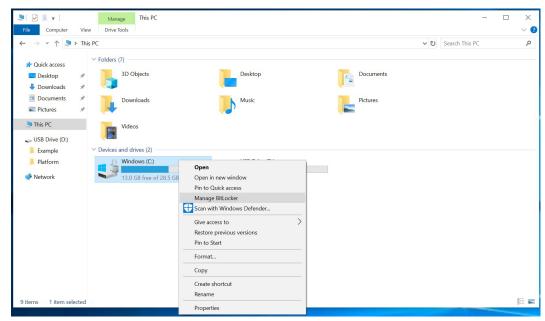


7. Wait for the encryption process to complete and then click **Close**.

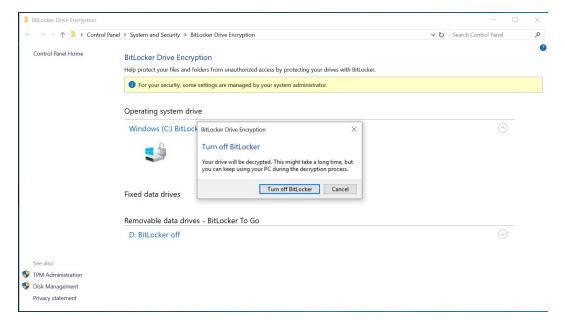


## **Disabling the BitLocker**

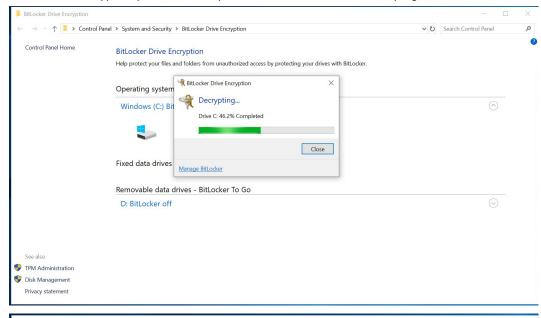
1. In the Windows Devices and drives, right-click on the drive and select Manage BitLocker.

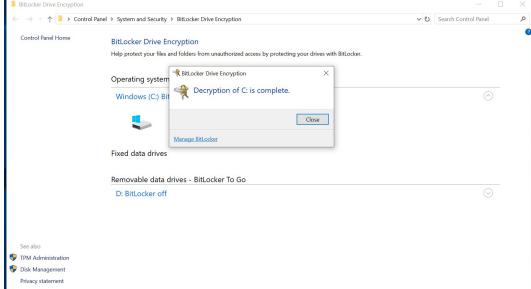


2. Click on Turn off BitLocker.

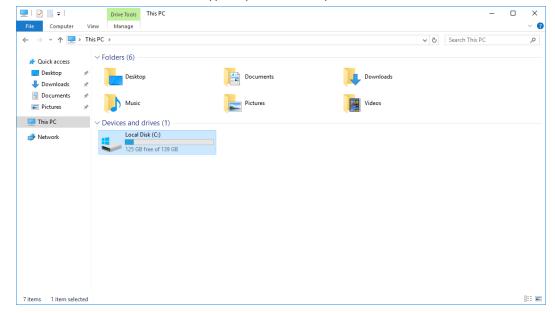


3. Wait for the decryption process to complete and click **Close** to exit the program.





4. Check the disk status after the decryption process is completed.



# **Configuring RAID**

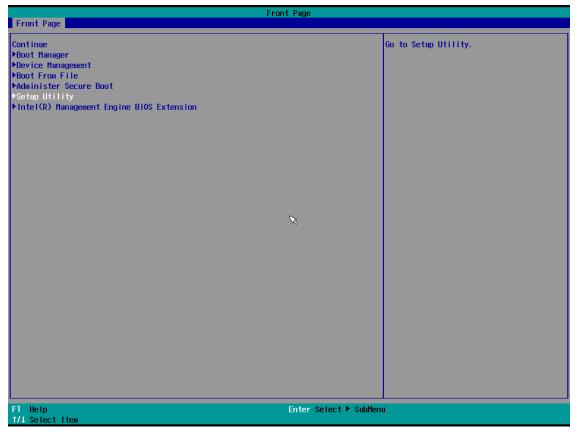
This chapter describes the setup process for RA	RAIC	for	process	setup	the	describes	chapter	This
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The following topics are covered in this chapter:

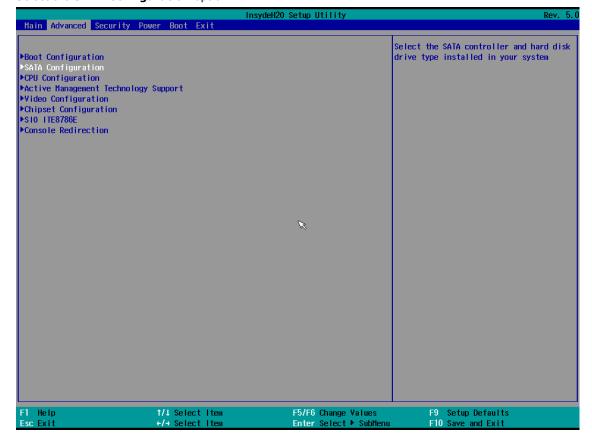
- ☐ Changing the RAID Mode
  - > Changing the SATA Mode from AHCI to RAID
- ☐ Creating a RAID Disk in BIOS
- □ Replacing a Disk
- ☐ Removing a RAID Volume From the BIOS

## **Changing the RAID Mode**

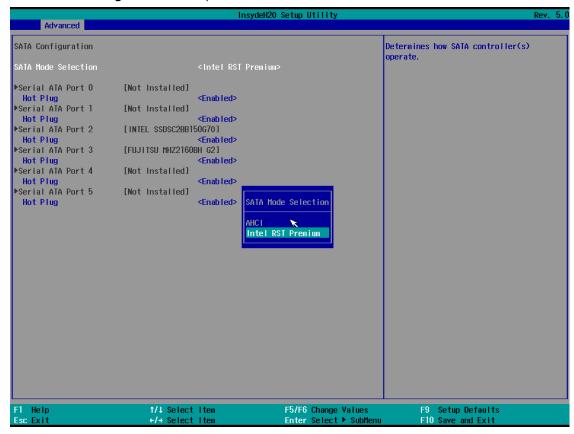
- 1. Power on the computer and press **F2** to enter the BIOS menu.
- 2. Select the **Setup Utility** option.



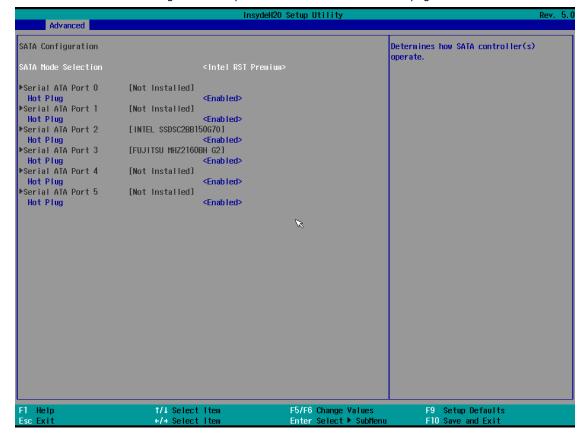
3. Select the SATA Configuration option.



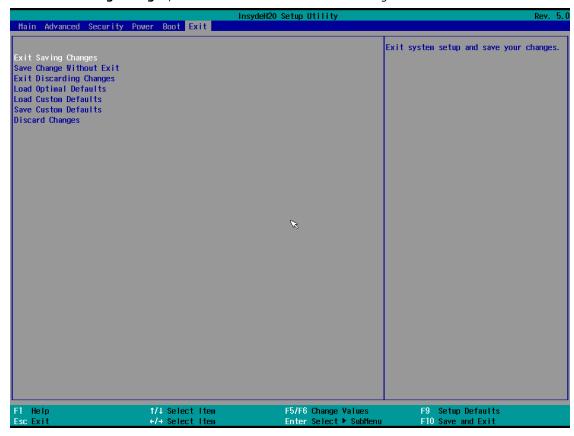
- 4. Select the **SATA Mode Selection** followed by the **Intel RST Premium** option.
- 5. Enable the **Hot Plug** function on all ports.



6. Press F10 to save the settings and then press ESC to return to the main page.



7. Select **Exit Saving Changes**, and then select **Yes** to save the settings.



### Changing the SATA Mode from AHCI to RAID

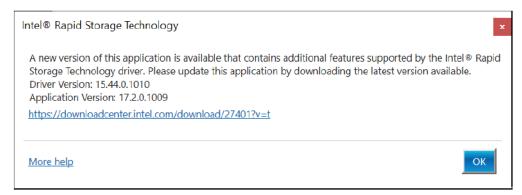
The Moxa OS image is created using the AHCI mode. If you need to set up the RAID mode in the default Moxa OS image, you must reinstall the Intel® Rapid Storage Technology (RST) driver.

To reinstall the Intel® RST driver, do the following:

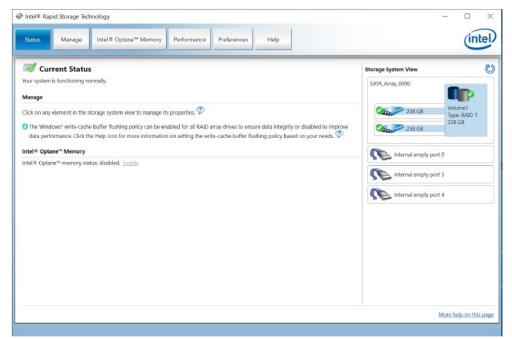
1. Run the Intel® Rapid Storage Technology tool.



If the system displays the following message, you must reinstall the Intel® RST driver.

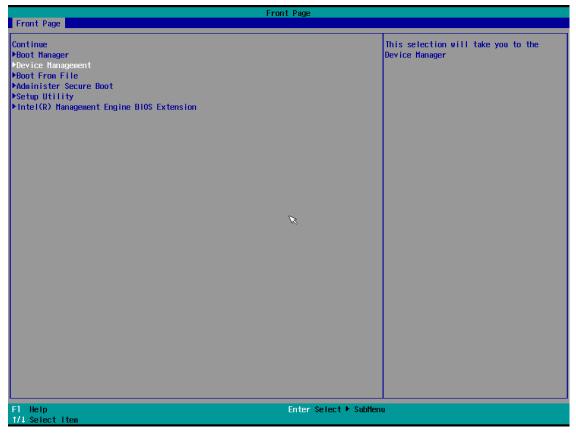


- 2. Uninstall the current Intel® RST driver.
- 3. Download the latest driver from Moxa's website or Intel's driver download page.
- 4. Install the latest Intel® RST driver.
- 5. Run the Intel® Rapid Storage Technology tool to see the current disk status.



# Creating a RAID Disk in BIOS

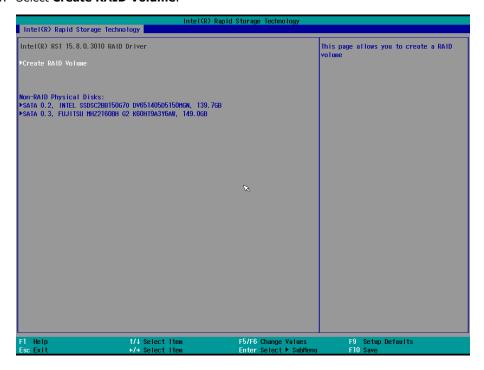
- 1. Power on the computer and press **F2** to enter the BIOS menu.
- 2. Select the **Device Management** option.



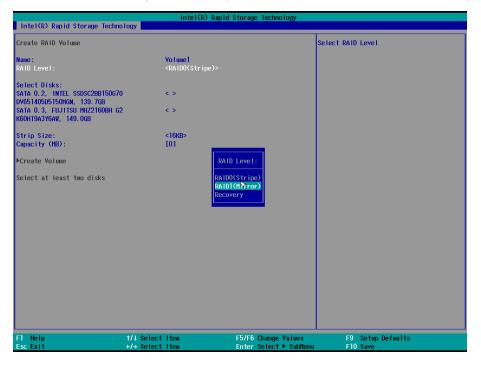
3. Select Intel® Rapid Storage Technology.

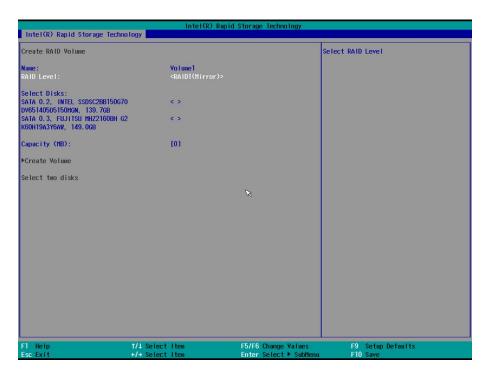


4. Select Create RAID Volume.

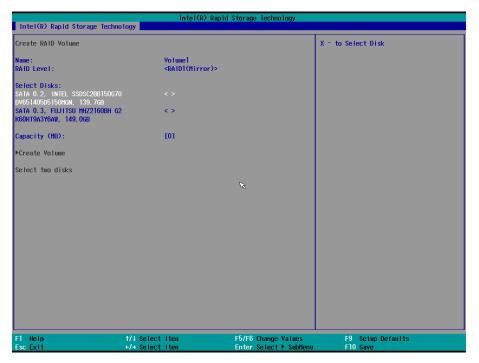


5. Select the **RAID Level** option and then press **Enter** to select the raid level; for example, **RAID1(Mirror)**.

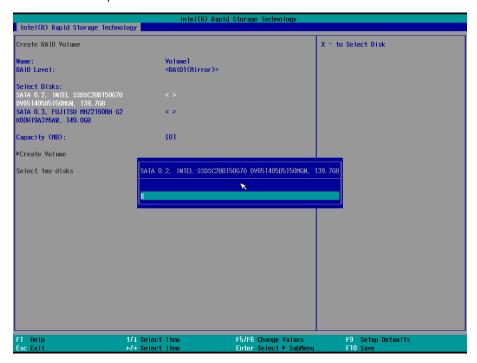




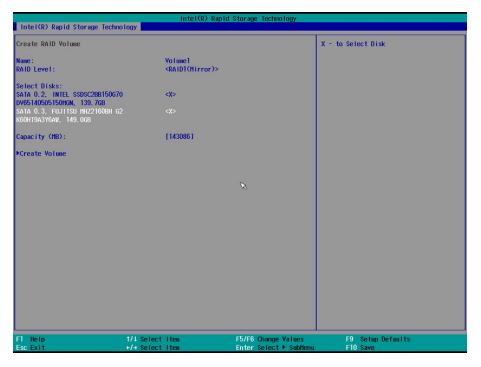
6. Select the disk.



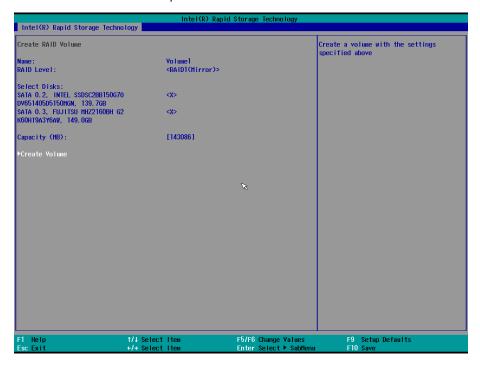
7. Enter x and then press **Enter**.



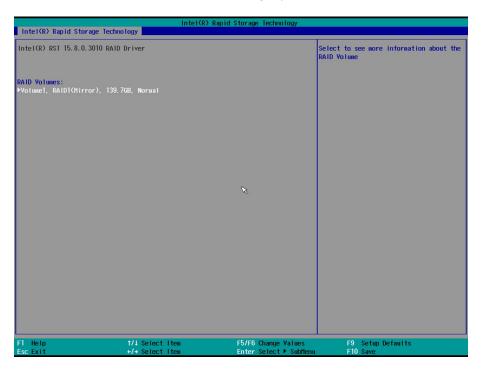
The disk is now marked with an x next to it to indicate the selection.



8. Select the **Create Volume** option.



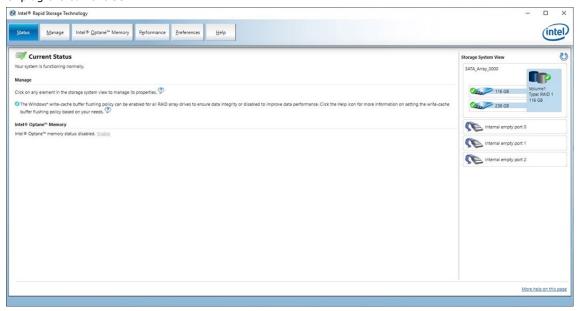
A RAID volume is created based on the settings specified.

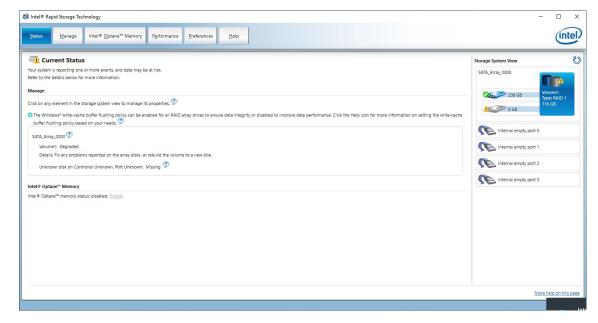


9. Press **F10** to save the settings.

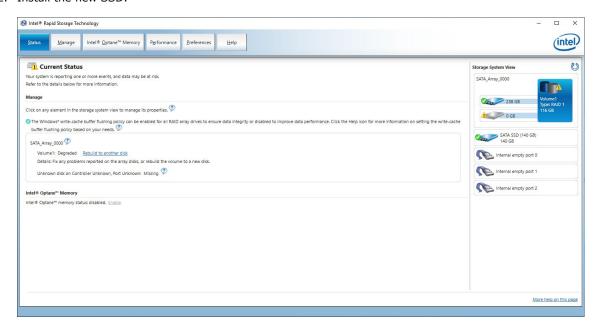
## Replacing a Disk

1. Unplug the current SSD.

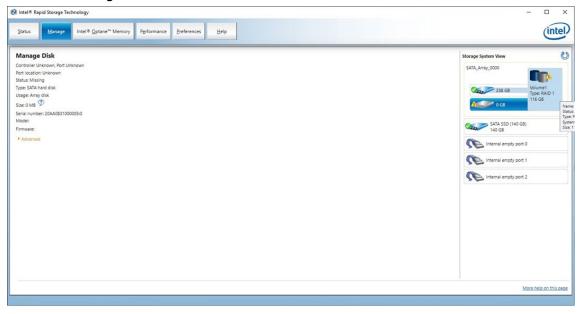




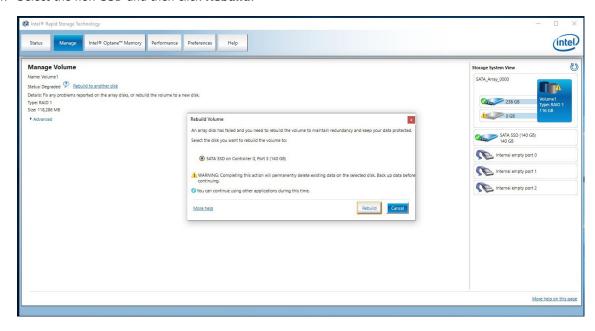
2. Install the new SSD.



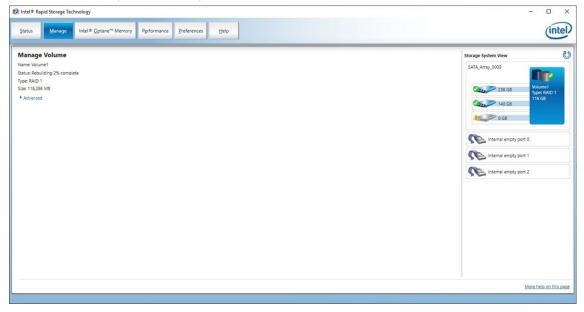
3. Click on the Manage tab.

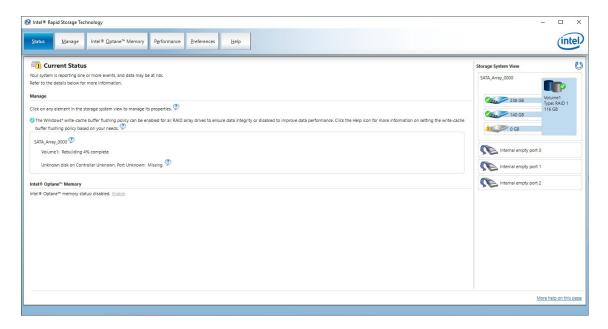


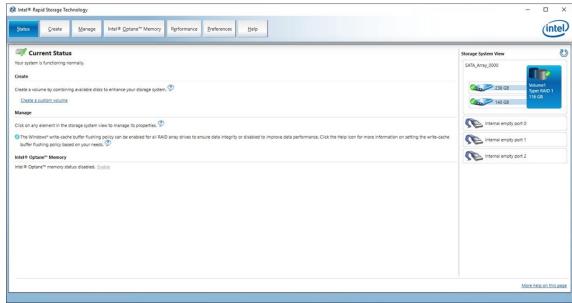
4. Select the new SSD and then click **Rebuild**.



5. Wait for the rebuild process to complete.

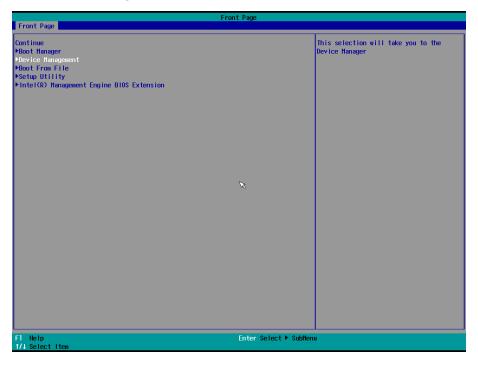






## Removing a RAID Volume From the BIOS

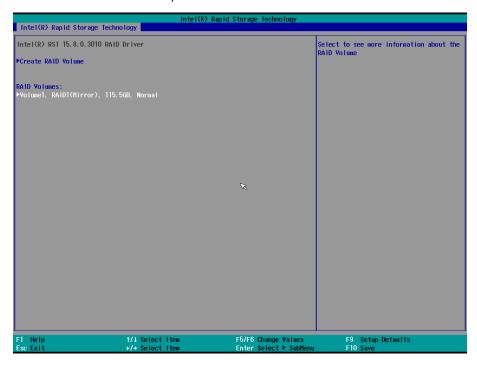
- 1. Power on the computer and press **F2** to enter the BIOS menu.
- 2. Select Device Management.



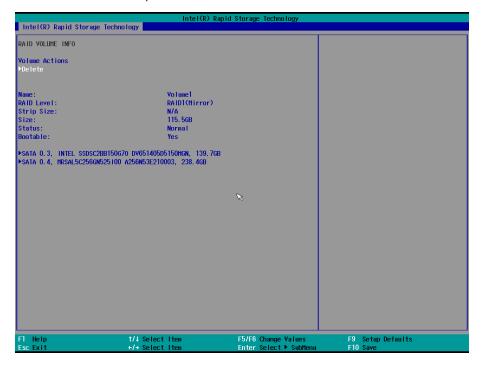
3. Select the Intel® Rapid Storage Technology option.



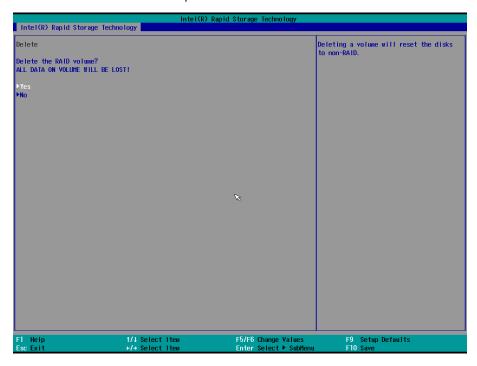
4. Select the RAID volume that you want to remove.



5. Select **Delete** and then press **Enter**.



6. Select **Yes** to confirm and then press **Enter**.



7. Press **F10** to save the settings.

# **Teaming**

This chapter describes the setup process for the Intel  $\ensuremath{\mathtt{R}}$  Teaming function.

The following topics are covered in this chapter:

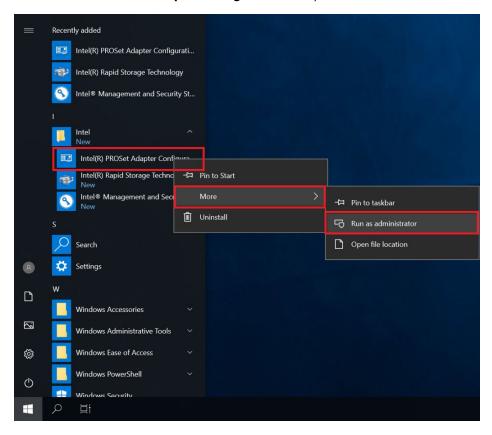
- ☐ Creating an Intel® Net Team
- ☐ Modifying an Intel® Net Team Member
  - > Adding an Intel® Net Team Member
  - > Removing an Intel® Net Team Member
- ☐ Removing an Intel® Net Team

V2406C Windows UM Teaming

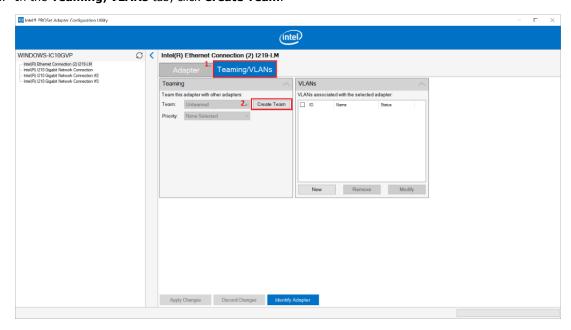
## **Creating an Intel® Net Team**

### Intel® Network Driver Version 25.0 and Higher

1. Run the Intel® PROSet Adapter Configuration Utility as administrator.

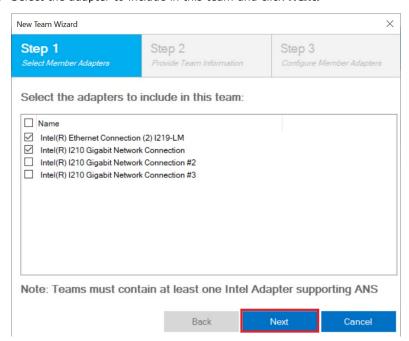


2. In the **Teaming/VLANs** tab, click **Create Team**.



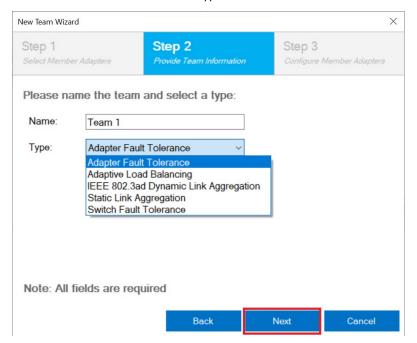
V2406C Windows UM Teaming

3. Select the adapter to include in this team and click **Next.** 



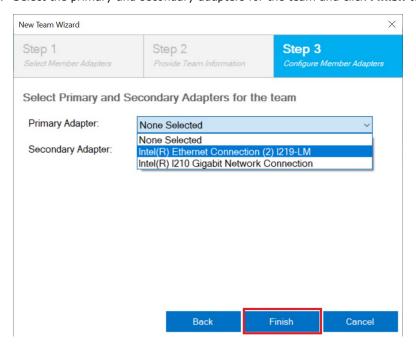
An Intel ANS team can contain a maximum of eight members.

4. Name the team and select a team type. Click **Next** to continue.



V2406C Windows UM Teaming

5. Select the primary and secondary adapters for the team and click Finish to create an Intel net team.



### **Intel® Network Driver Prior to Version 25.0**

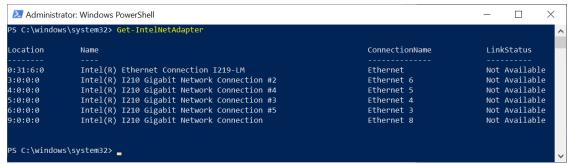
- 1. Run the Windows PowerShell as administrator.
- 2. Run the command:

Import-Module -Name "C:\Program Files\Intel\Wired
Networking\IcntelNetCmdlets\IntelNetCmdlets".



3. Run the New-IntelNetTeam command.

This command creates a new Intel ANS team consisting of one or more adapters. A team may consist of both Intel and non-Intel adapters. Adapter objects obtained using the Get-IntelNetAdapter command may be passed into this cmdlet using the TeamMembers parameter.



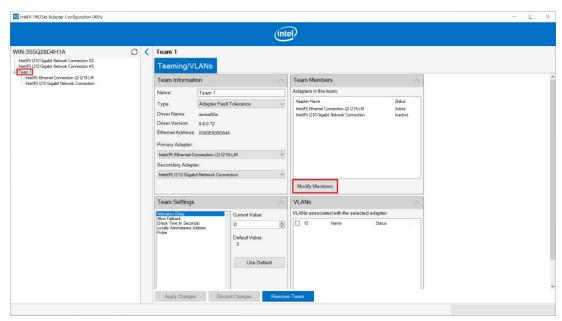
4. Check the Network adapters in the Windows Device Manager.

# **Modifying an Intel® Net Team Member**

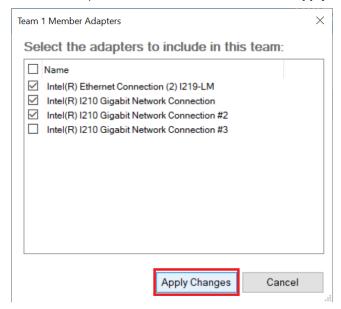
### Adding an Intel® Net Team Member

### **Intel® Network Driver Version 25.0 and Higher**

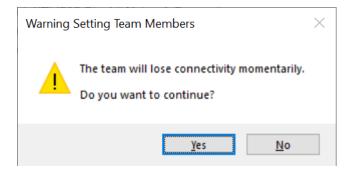
1. Select an Intel net team and click Modify Members.



2. Select the adapters to include in this team and click **Apply Changes**.

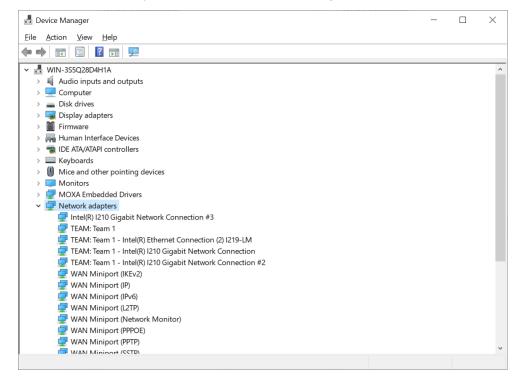


3. Click Yes to continue.



**NOTE** Modifying team members will cause the members to momentarily lose connectivity.

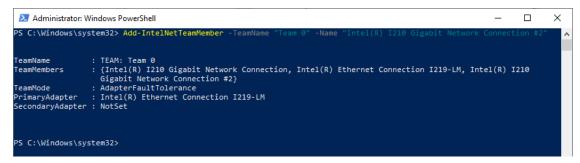
4. Check the Network adapters in the Windows Device Manager.



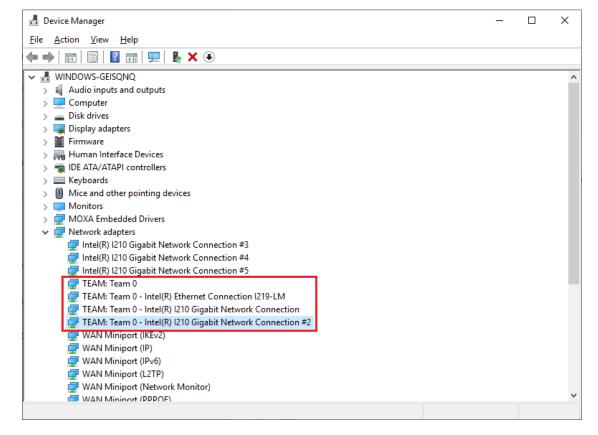
### Intel® Network Driver Prior to Version 25.0

1. Run the Add-IntelNetTeamMember command.

This command adds a new team member to an existing Intel® Advanced Network Services (Intel® ANS) Team. The new team member can be piped into the cmdlet or passed in using the adapter's name. An Intel ANS team can contain a maximum of eight members.



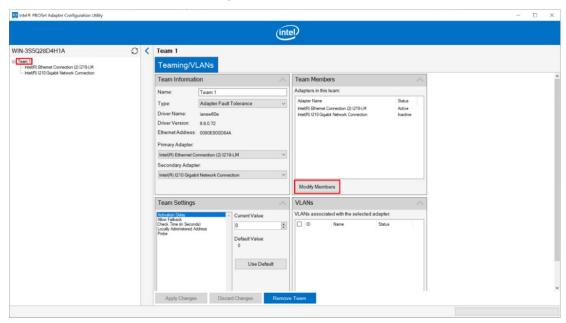
2. Check the Network adapters in the Windows Device Manager.



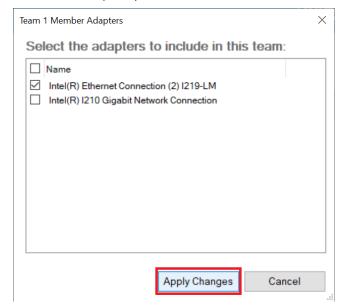
### Removing an Intel® Net Team Member

### **Intel® Network Driver Version 25.0 and Higher**

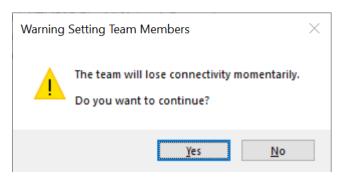
1. Select an Intel net team and click Modify Members.



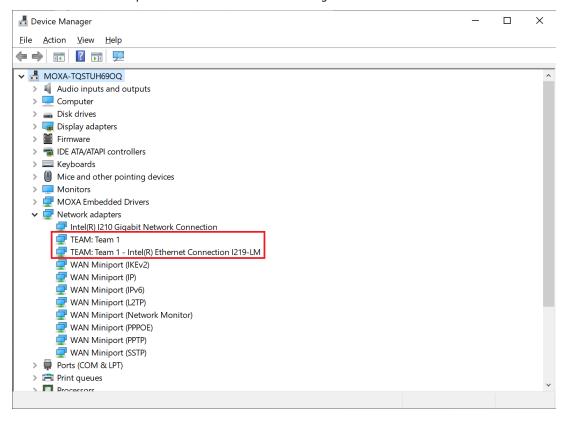
2. Uncheck the adapters you want to remove in this team and click **Apply Changes**.



3. Click **Yes** to continue.



4. Check the network adapters in the Windows Device Manager.



### Intel® Network Driver Prior to Version 25.0

 $1. \ \ \, \text{Run the } \textbf{Remove-IntelNetTeamMember} \ \text{command}.$ 

This command allows users to remove a team member from an Intel ANS team. The team member can be piped into the cmdlet or passed in using the team member's name.

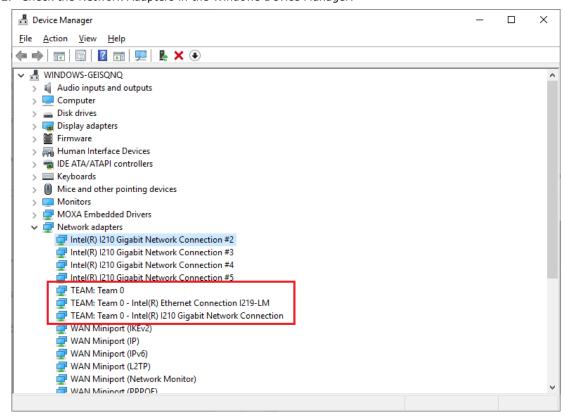
```
Administrator: Windows PowerShell

PS C:\Windows\system32> Remove-IntelNetTeamMember -Name "Intel(R) I210 Gigabit Network Connection #2"

TeamName : TEAM: Team 0
TeamNembers : {Intel(R) I210 Gigabit Network Connection, Intel(R) Ethernet Connection I219-LM}
TeamNode : AdapterFaultTolerance
PrimaryAdapter : Intel(R) Ethernet Connection I219-LM
SecondaryAdapter : NotSet

PS C:\Windows\system32>
```

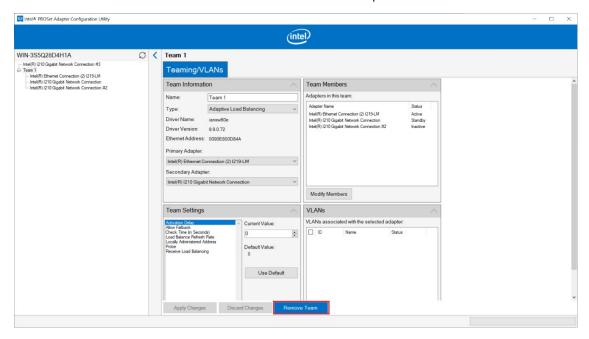
2. Check the Network Adapters in the Windows Device Manager.



## Removing an Intel® Net Team

### Intel® Network Driver Version 25.0 and Higher

Select an Intel net team and click Remove Team to remove the specified Intel ANS team.



### **Intel® Network Driver Prior to Version 25.0**

Run the Remove-IntelNetTeam command. Removes the specified Intel ANS team.



# **Unified Write Filter**

This chapter describes how to use the Unified the Write Filter (UWF).

To use the UWF, you must first install the feature and enable (optionally configure) it.

The first time you enable UWF on your device, UWF makes the following changes to your system to improve its performance:

- · Paging files are disabled.
- System restore is disabled.
- SuperFetch is disabled.
- · File indexing service is turned off.
- Fast boot is disabled.
- · Defragmentation service is turned off.
- BCD setting bootstatuspolicy is set to ignoreallfailures.

After UWF is enabled, you can select a drive that you want to protect and start using UWF. UWF can help you manage PCs and devices remotely using WMI.

The following topics are covered in this chapter:

- ☐ Turning on UWF on a Running PC
- ☐ Installing UWF Using WMI

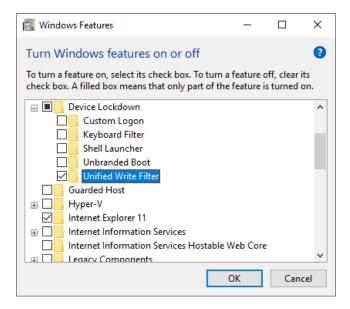
V2406C Windows UM Unified Write Filter

# **Turning on UWF on a Running PC**

- 1. Install UWF.
  - a. In the Windows Start window, type Turn Windows features on or off.
  - b. Open the Windows Features window and expand the Device Lockdown node.
  - c. Select Unified Write Filter and click OK.

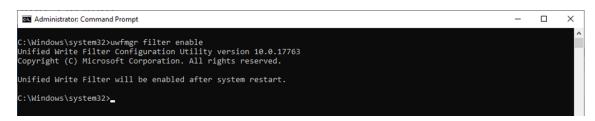
Windows searches for the required files and displays a progress bar. Once the files are found, Windows applies the changes. When the changes are complete, a message to this effect is displayed.

d. Click Close.



2. Enable the following filter as an Administrator:

cmd uwfmgr filter enable



3. Enable write protection for a drive:

cmd uwfmgr.exe volume protect C:

```
C:\Windows\system32>uwfmgr filter enable
Unified Write Filter Configuration Utility version 10.0.17763
Copyright (C) Microsoft Corporation. All rights reserved.
Unified Write Filter will be enabled after system restart.
C:\Windows\system32>uwfmgr.exe volume protect C:
Unified Write Filter Configuration Utility version 10.0.17763
Copyright (C) Microsoft Corporation. All rights reserved.

The volume C: will be protected by Unified Write Filter after system restart.
C:\Windows\system32>
```

4. Restart your computer.

V2406C Windows UM Unified Write Filter

5. Confirm that UWF is running:

cmd uwfmgr.exe get-config

```
Administrator Command Prompt

C:\Windows\system32>uwfmgr.exe get-config
Unified Write Filter Configuration Utility version 10.0.17763
Copyright (C) Microsoft Corporation. All rights reserved.

Current Session Settings

FILTER SETTINGS
    Filter state: OFF
    Pending commit: N/A
    Shutdown pending:No

SERVICING SETTINGS
    Servicing State: OFF

OVERLAY SETTINGS
    Type: RAM
    Maximum size: 1024 MB
    Warning Threshold: 512 MB
    Critical Threshold: 1024 MB
    Freespace Passthrough: OFF
    Persistent: OFF
    Reset Mode: N/A
```

## **Installing UWF Using WMI**

If you have already installed Windows on your computer and you do not want to use a provisioning package, you can configure UWF by using Windows Management Instrumentation (WMI) providers. To turn on UWF using WMI, use the UWF\_Filter function, specifically the UWF\_Filter.Enable method in one of the following ways:

- Use the WMI providers directly in a PowerShell script
- Use the WMI providers directly in an application
- Use the command line tool, uwfmgr.exe

**NOTE** You must restart your computer after you turn on or turn off UWF for the changes to take effect.

You can also change the settings after you turn on UWF. For example, you can move the page file location to an unprotected volume and re-enable paging files.



### **IMPORTANT!**

If you add UWF to your image by using SMI settings in the unattend.xml file, turning on UWF only sets the bootstatuspolicy BCD setting and turns off the defragmentation service. You have to manually turn off the other features and services if you want to increase the performance of UWF.

After the device is restarted, UWF maintains configuration settings for the current session in a registry. UWF automatically excludes these registry entries from its filter. Static configuration changes do not take effect until after a device restart; the changes are saved in registry entries for use in the next session. Dynamic configuration changes occur immediately and persist after a device restart.

# **Disk Hot Swap Function**

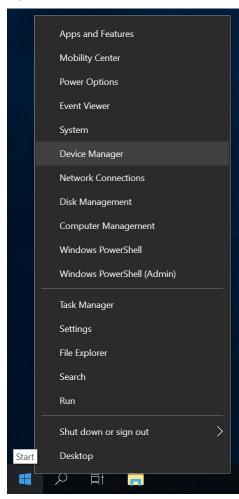
This chapter describes the setup process for the disk hot swap function.

The following topics are covered in this chapter:

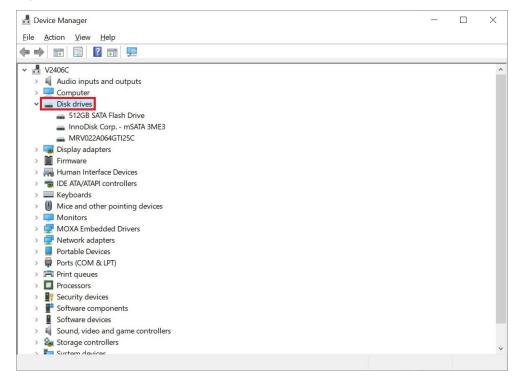
- ☐ Setting Up the Disk Removal Policy
- ☐ Setting Up the Drive Actions
  - Default Actions
- □ Unmounting and Mounting Disks
  - > Unmounting a Disk Drive
  - ➤ Mounting a Disk Drive
- ☐ Hot Swap Function Notifications

# **Setting Up the Disk Removal Policy**

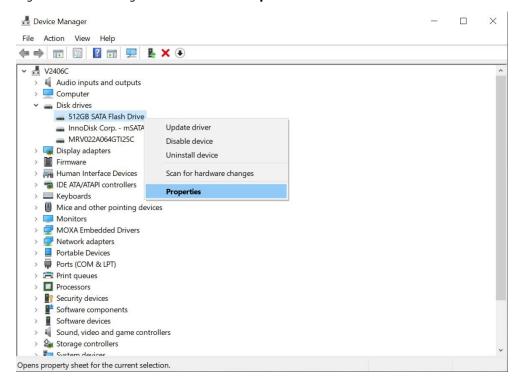
1. Right-click on the Windows Start icon and select **Device Manager**.



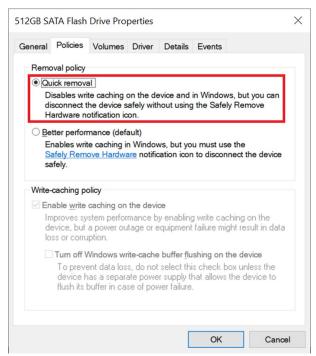
2. Expand the **Disk drives** node.



3. Right-click on the target drive and select **Properties**.



4. In the Policies tab, select Quick removal and click OK.

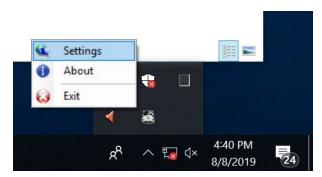


5. Click **Yes** to restart the computer and apply the new settings.

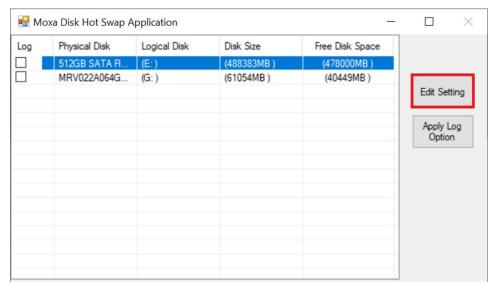


# **Setting Up the Drive Actions**

1. Right-click on the Disk Hot Swap application icon on the Windows taskbar and select **Settings**.

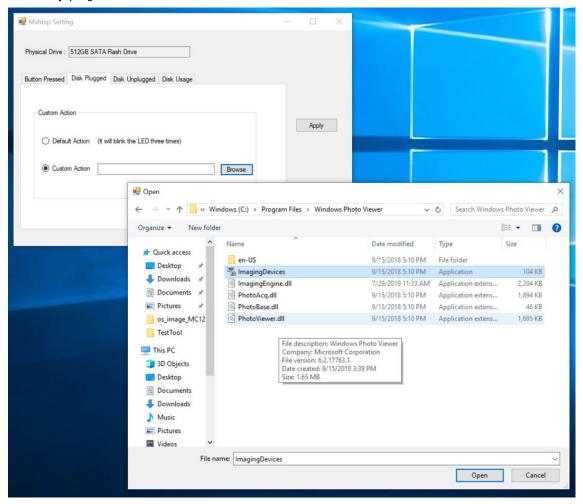


2. Select the target drive and click **Edit Setting**.



3. Open an event tab (Button Pressed, Disk Plugged, Disk Unplugged, or Disk Usage) and select Custom Action.

4. Associate the application that you want to run as the custom action when the event is triggered. The application will run in the background. The new settings will take effect the next time you run the **Disk Hot Swap** program.



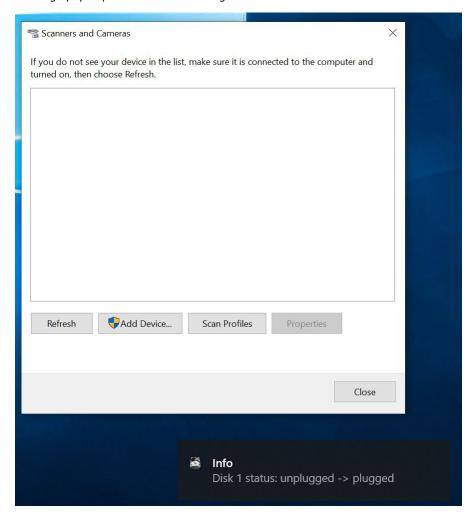


### **IMPORTANT!**

The action for the  ${\bf Button\ Pressed}$  event is triggered only when the button is pressed for more than 3 seconds.

### **Example**

The **Scanners and Cameras** application is run after the event **Disk Plugged** is triggered. A notification message pops up to indicate the change in status of the device.



### **Default Actions**

If you do not configure a Custom Action, the following default actions are triggered by the events.

- 1. **Button Pressed:** Disk unmount procedure is triggered when the button is pressed for over 3 seconds.
- 2. Disk Plugged: The disk drive list in the Windows Device Manager is refreshed after a few seconds.
- 3. **Disk Unplugged:** The disk drive list in the Windows Device Manager is refreshed after a few seconds.
- Disk Usage: A notification on the disk usage is displayed.
   This event is triggered if on Check Disk Usage, the disk usage is equal to or higher than the disk usage threshold.

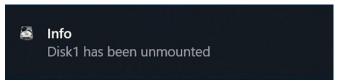
# **Unmounting and Mounting Disks**

### **Unmounting a Disk Drive**

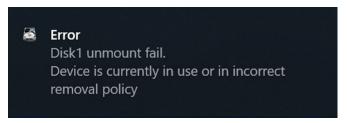
Press the button of the target disk for more than three seconds.
 The disk unmount procedure will start after the **Button is pressed** notification is displayed.



2. The **Disk has been unmounted** notification is displayed after the disk has been successfully unmounted.



If the disk unmount process fails, you will see the following message. Ensure that the target disk removal policy is set to **Quick removal** and the target disk is not busy before triggering the unmount process again.



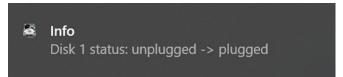
3. After the disk has been unmounted, unplug the disk from your computer after you see the following notification.



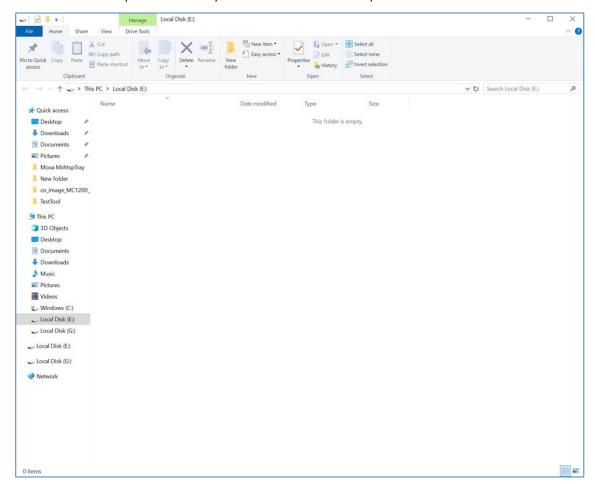
This completes the disk unmounting process.

### **Mounting a Disk Drive**

Insert the disk into the computer.
 The following notification is displayed.



2. The disk folder will open automatically after the disk is successfully mounted.



# **Hot Swap Function Notifications**

Notification	Notification Content	Description
Туре		
Info	Button is pressed	Displayed when a button is pressed for more than 3
		seconds.
Info	Disk has been unmounted	Displayed after a disk is successfully unmounted.
Info	Disk status: unplugged -> plugged	Displayed after a disk is plugged into the computer.
Info	Disk status: plugged -> unplugged	Displayed after a disk is unplugged from the computer.
Info	Partition is over usage, execute user	Displayed when the disk usage is over a predefined
	program	threshold. A user-specified program is run after this
		event is triggered.
Info	Partition is over usage, use system	Displayed when the disk usage is over a predefined
	default action	threshold. A user-specified program is run after this
		event is triggered.
Error	Disk unmount fail. Device is currently	Displayed when disk unmount process fails; disk is in
	in use or in incorrect removal policy	busy state or the removal policy is incorrect.
Error	Invalid handle	Displayed when an internal error occurs.
Application	Starting Moxa Disk Hot Swap	Displayed when the Moxa Disk Hot Swap application
	Application	starts up.
Application	Stopping Moxa Disk Hot Swap	Displayed when the Moxa Disk Hot Swap application
	Application	stops running.

# **Moxa IO Controller Utility**

This chapter describes how to use the Moxa IO Controller utility.

To use the Moxa IO Controller utility, first install the utility and enable the utility to configure the DIO, UART mode, and SIM settings. After the installation process is complete, run the Windows command prompt as an Administrator and change the path to C:\Program Files\Moxa\Moxa Computer IO Controller.



The following topics are covered in this chapter:

- ☐ Setting the DIO Status
- ☐ Setting the UART Mode
- ☐ Setting the SIM Status

# **Setting the DIO Status**

Type the command mx-dio-ctl --help command to see the instructions on using this utility and follow them to get or set the DIO status.



### **IMPORTANT!**

The DIN and DOUT indices start at 0. Even though the console output starts at 1, the indices still start at 0.

```
C:\Program Files\Moxa\Moxa Computer IO Controller>mx-dio-ctl --help
mx-dio-ctl 1.0.1993.0
Copyright (C) 2019 Moxa Inc. All rights reserved.
USAGE:
Get value from DIN port 1:
mx-dio-ctl -i
mx-dio-ctl -i
Get value from DOUT port 1:
mx-dio-ctl -o 1
Set DOUT port 2 value to HIGH:
mx-dio-ctl -m 1 -o 2

-i -i <#DIN index> (Start from 0)

-o -o <#DOUT index> (Start from 0)

-m -m <status>
0 --> LOW
1 --> HIGH

--help Display this help screen.
--version Display version information.

C:\Program Files\Moxa\Moxa\Moxa Computer IO Controller>
```

### **Example:**

```
C:\Program Files\Moxa\Moxa Computer IO Controller>mx-dio-ctl -i 0
DIN port 0 status: 1

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-dio-ctl -o 0
DOUT port 0 status: 1

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-dio-ctl -o 0 -m 0
DOUT port 0 status: 0

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-dio-ctl -i 0
DIN port 0 status: 0

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-dio-ctl -i 0
DIN port 0 status: 0

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-dio-ctl -i 0
DIN port 0 status: 0
```

## **Setting the UART Mode**

Type the mx-uart-ctl --help command to see instructions on using this utility and follow the onscreen instructions to get or set the UART mode.



### **IMPORTANT!**

The UART index starts from 0. Even though the console output starts at 1, the index still starts at 0.

```
C:\Program Files\Moxa\Moxa Computer IO Controller>mx-uart-ctl --help
mx-uart-ctl 1.0.1903.0
Copyright (C) 2019 Moxa Inc. All rights reserved.
USAGE:
Get uart mode from port 2:
mx-uart-ctl -p 2
Set port I to mode RS-422:
mx-uart-ctl -m 2 -p 1

-p Required. -p <#port index> (Start from 0)

-m -m <#suart mode>
0 --> set to RS432 mode
1 --> set to RS485-2W mode
2 --> set to RS422 mode
--help Display this help screen.
--version Display version information.

C:\Program Files\Moxa\Moxa Computer IO Controller>
```

### **Example**

```
C:\Program Files\Moxa\Moxa Computer IO Controller>mx-uart-ctl -p θ

Current uart mode is RS232 interface.

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-uart-ctl -p θ -m 1

Set OK.

Current uart mode is RS485-2W interface.

C:\Program Files\Moxa\Moxa Computer IO Controller>__
```

## **Setting the SIM Status**

Type the mx-sim-ctl --help command to see instructions on using this utility and follow the onscreen instructions to get or set the status of the SIM card.



### **IMPORTANT!**

The SIM card index starts from 0. Even though the console output starts at 1, the SIM card index still starts at 0.

```
C:\Program Files\Moxa\Moxa Computer IO Controller>mx-sim-ctl.exe --help
mx-sim-ctl 1.0.1906.0
Copyright (C) 2019 Moxa Inc. All rights reserved.
USAGE:
mx-sim-ctl -i 1
Set sim 1 to slot 1:
mx-sim-ctl -i 1 -m 1
-i Required. -i <#SIM port index> (Start from 0)
-m -n <sim slot
0 --> SIM slot 0
1 --> SIM slot 1

--help Display this help screen.
--version Display version information.

C:\Program Files\Moxa\Moxa Computer IO Controller>_
```

### **Example**

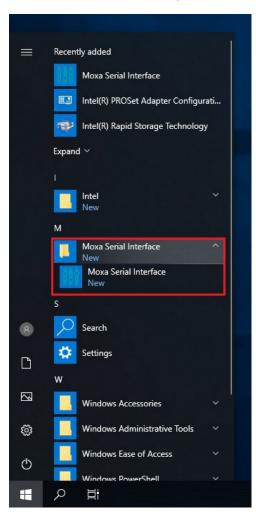
```
C:\Program Files\Moxa\Moxa Computer IO Controller>mx-sim-ctl.exe -i 0
SIM 0 slot: 1
C:\Program Files\Moxa\Moxa Computer IO Controller>mx-sim-ctl.exe -i 0 -m 0
SIM 0 slot: 0
C:\Program Files\Moxa\Moxa Computer IO Controller>
```

# **Moxa Serial Interface Utility**

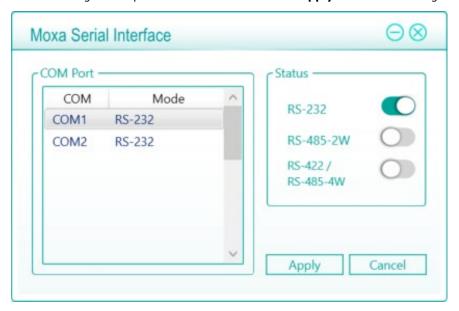
In this chapter, we describe how to use the Moxa Serial Interface utility to set the UART mode in your computer's serial interface.

# **Setting the UART Mode**

- 1. Install the Moxa Serial Interface utility.
- 2. From the Windows **Start** menu, run the **Moxa Serial Interface** utility.



3. Select the target COM port and UART mode and click **Apply** to save the settings.



# **IO Control API**

This chapter describes how to use the IO Control API.

The following topics are covered in this chapter:

### □ Downloading the API

### ☐ mxdgio

- GetDinStatus
- > GetDoutStatus
- > SetDoutStatus

### □ mxsp

- ➢ GetUartMode
- SetUartMode

### □ mxwdg

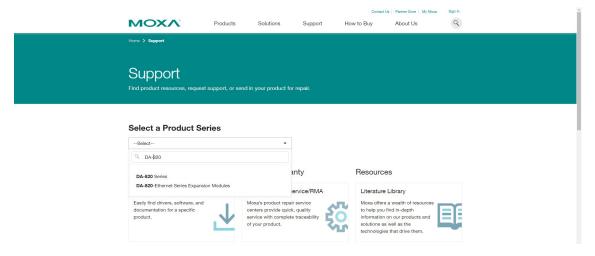
- mxwdg\_open
- mxwdg\_refresh
- mxwdg\_close

### □ mxsim

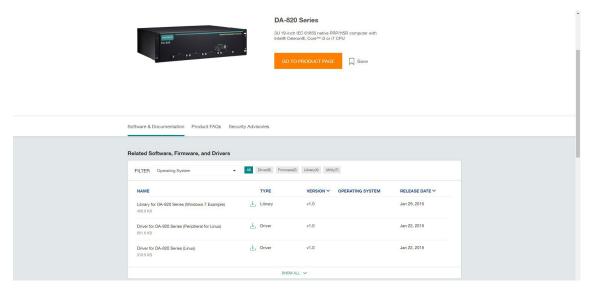
- > GetSIMSlot
- > SetSIMSlot

# **Downloading the API**

- 1. Access the Moxa support page: <a href="https://www.moxa.com/en/support">https://www.moxa.com/en/support</a>
- 2. Select the product series (example: DA-820).



3. Download the related files.



# mxdgio

The mxdgio library operates on the digital I/Os and consists of the following:

- GetDinStatus
- GetDoutStatus
- SetDoutStatus

### **GetDinStatus**

### **Syntax**

int GetDinStatus(int port);

### **Description**

Gets the status of a digital input port.

### **Parameters**

port: The index of the digital input port (starts at 0).

### **Return Value**

The status of the digital input port; 0 for low and 1 for high.

### **Error codes**

The following error codes can be retrieved by the **DIO\_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxdgio library initialization failed. Can't open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

### **Requirements**

Name	Items
Header	mxdgio.h
Library	mxdgio.lib
DLL	mxdgio.dll
Profile	MxdgioProfile[ <i>ModelName</i> ].json

### **GetDoutStatus**

### **Syntax**

int GetDoutStatus(int port);

### **Description**

Gets the status of a digital output port.

### **Parameters**

port: The index of the digital output port; starts at 0.

### **Return Value**

The status of the digital output port; 0 for low and 1 for high.

### **Error codes**

The following error codes can be retrieved by the **DIO\_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxdgio library initialization has failed. Cannot open the json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

### **Requirements**

Name	Items
Header	mxdgio.h
Library	mxdgio.lib
DLL	mxdgio.dll
Profile	MxdgioProfile[ModelName].json

### **SetDoutStatus**

### **Syntax**

int SetDoutStatus(int port, int status);

### **Description**

Sets the status of a digital output port.

### **Parameters**

port: The index of the digital output port; starts at 0.

status: The status of the digital output port; 0 for low and 1 for high.

#### **Return Value**

Returns the value 0 if the digital output status is successfully set.

### **Error codes**

The following error codes can be retrieved by the **DIO\_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxdgio library initialization failed. Can't open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET_STATUS_ERR	-3	Set the status fail. Status is defined with a bad format.

### **Requirements**

Name	Items
Header	mxdgio.h
Library	mxdgio.lib
DLL	mxdgio.dll
Profile	MxdgioProfile[ModelName].json

## mxsp

The mxsp library operates on the serial port and consists of the following:

- GetUartMode
- SetUartMode

### **GetUartMode**

### **Syntax**

int GetUartMode(int port);

### **Description**

Gets the status of the UART port.

### **Parameters**

port: The index of the UART port; starts at 0.

### Return Value

The mode of a UART interface; 0 for RS-232, 1 for RS-485-2w, and 2 for RS-422.

### **Error codes**

The following error codes can be retrieved by the **UART\_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxsp library initialization failed. Can't open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

### **Requirements**

Name	Items
Header	mxsp.h
Library	mxsp.lib
DLL	mxsp.dll
Profile	MxspProfile[ <i>ModelName</i> ].json

### **SetUartMode**

### **Syntax**

int SetUartMode(int port, int mode);

### **Description**

Sets the status of the UART port.

### **Parameters**

port: The index of the UART port; starts at 0.

mode: The mode of a UART interface; 0 for RS-232, 1 for RS-485-2w, and 2 for RS-422.

### **Return Value**

Returns 0 if the UART mode is successfully set.

### **Error codes**

The following error codes can be retrieved by the **UART\_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxsp library initialization failed. Can't open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET_STATUS_ERR	-3	Set the status fail. Status is defined with a bad format.

### **Requirements**

Name	Items
Header	mxsp.h
Library	mxsp.lib
DLL	mxsp.dll
Profile	MxspProfile[ModelName].json

# mxwdg

The mxwdg library operates on the watchdog and consists of the following:

- mxwdg\_open
- mxwdg\_refresh
- mxwdg\_close

### mxwdg\_open

### <u>Syntax</u>

PVOID mxwdg\_open(unsigned long time);

### **Description**

Initializes the watchdog timer.

### **Parameters**

time: The interval at which the watchdog timer is refreshed; the unit is seconds.

### Return Value

Returns the pointer to the watchdog handle; returns -1 on failure to initialize the watchdog timer.

#### **Requirements**

Name	Items
Header	mxwdg.h
Library	mxwdg.lib
DLL	mxwdg.dll

### mxwdg\_refresh

### **Syntax**

int mxwdg\_refresh(PVOID fd);

### **Description**

Refreshes the watchdog timer.

### **Parameters**

fd: The handle of the watchdog timer.

### **Return Value**

Returns o on success; otherwise, the function has failed.

### **Requirements**

Name	Items
Header	mxwdg.h
Library	mxwdg.lib
DLL	mxwdg.dll

### mxwdg\_close

### **Syntax**

void mxwdg\_close(PVOID fd);

### **Description**

Disables the watchdog timer.

### **Parameters**

fd: The handle of the watchdog timer.

### **Return Value**

This function does not return a value.

### Requirements

Name	Items
Header	mxwdg.h
Library	mxwdg.lib
DLL	mxwdg.dll

### mxsim

The mxsim library operates on the SIM slot index and consists of the following:

- GetSIMSlot
- SetSIMSlot

### **GetSIMSlot**

### **Syntax**

int GetSIMSlot(int port);

### **Description**

Gets the SIM card slot index number.

### **Parameters**

port: The index of the SIM card slot; starts at 0.

#### **Return Value**

The SIM card slot number; 0 for SIM 0 slot, 1 for SIM 1 slot.

### **Error codes**

The following error codes can be retrieved by the **SIM\_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxsim library initialization failed. Can't open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

### **Requirements**

Name	Items
Header	mxsim.h
Library	mxsim.lib
DLL	mxsim.dll
Profile	MxsimProfile[ModelName].json

### **SetSIMSlot**

### **Syntax**

int GetSIMSlot(int port);

### **Description**

Sets the SIM card slot index.

### **Parameters**

port: The index of the SIM card slot; starts at 0.

 $\mathit{slot} \colon \mathsf{The} \ \mathsf{SIM} \ \mathsf{card} \ \mathsf{slot} \ \mathsf{of} \ \mathsf{a} \ \mathsf{SIM} \ \mathsf{number}; \ \mathsf{0} \ \mathsf{is} \ \mathsf{SIM} \ \mathsf{0} \ \mathsf{slot}, \ \mathsf{1} \ \mathsf{is} \ \mathsf{SIM} \ \mathsf{1} \ \mathsf{slot} \ .$ 

### **Return Value**

Returns 0 if the SIM card slot of the SIM number is successfully set.

### **Error codes**

The following error codes can be retrieved by the **SIM\_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxsim library initialization failed. Can't open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET_STATUS_ERR	-3	Set the status fail. Status is defined with a bad format.

### Requirements

Name	Items
Header	mxsim.h
Library	mxsim.lib
DLL	mxsim.dll
Profile	MxsimProfile[ModelName].json

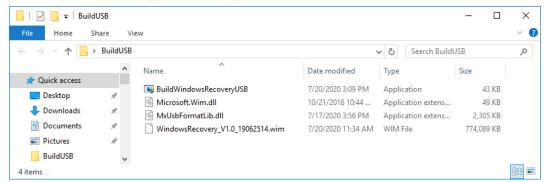
# **Windows Recovery**

This chapter describes the setup process of the Windows Recovery function.	
The following topics are covered in this chapter:	

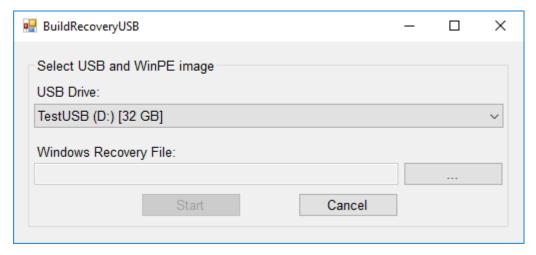
- □ Preparing the USB device
- ☐ Booting From the USB Disk
- ☐ System Image Backup
- ☐ Restoring the System From a Backup

# **Preparing the USB device**

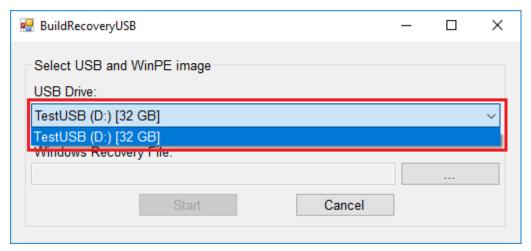
1. Contact Moxa technical support for the required files.



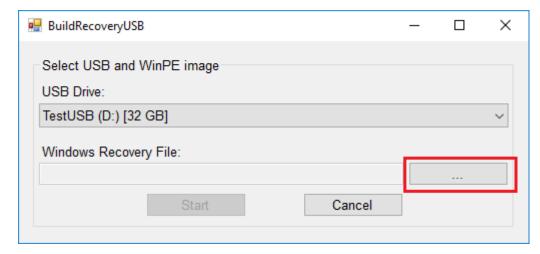
2. Run BuildWindowsRecoveryUSB.exe.

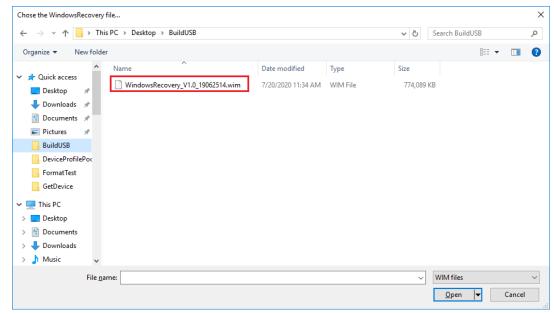


3. Select the USB drive that can be formatted.



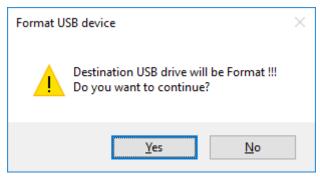
4. .Click ... to browse to the folder where the files are located and select the **wim** file.



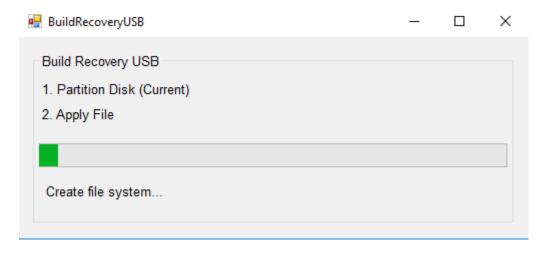


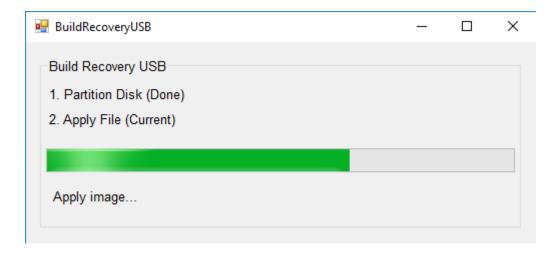
5. Click **Start** and make sure the selected USB can be formatted. click **Yes** to start creating the recovery USB.



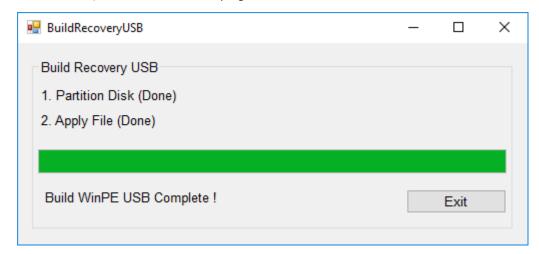


6. Wait for the process finished, the program will format the USB device and create a UEFI bootable volume and a WinPE volume. There may appear some windows about folder information, just skip it. You can close the window after the process finishes.

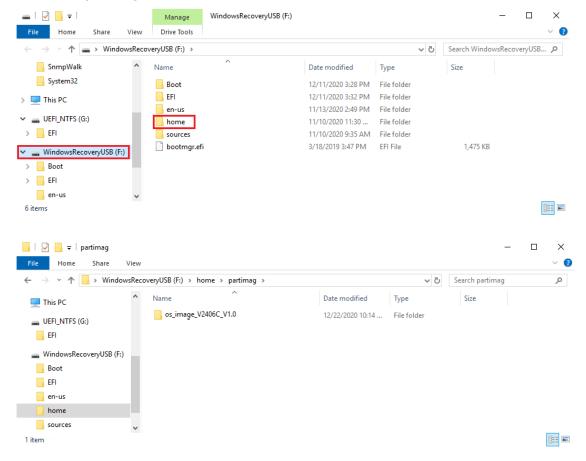




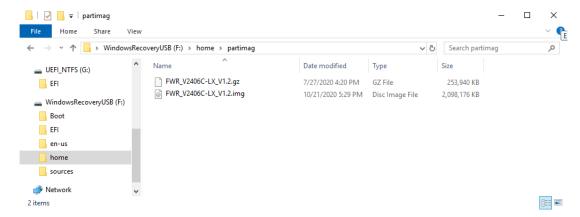
7. When finished, click **Exit** to close the program.



8. To create a recovery USB disk with the Windows 10 image, copy the **os\_image\_ModelName** directory to the **\home\partimag\** folder in the USB drive.

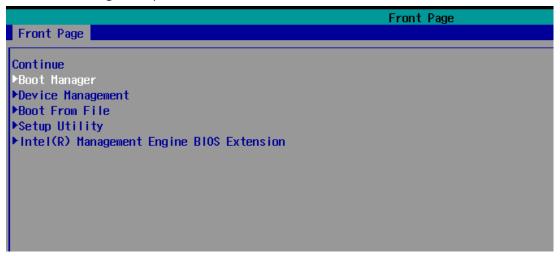


9. To create a recovery USB disk with a Linux image, copy the **ModelName.gz** or **ModelName.img** image file to the**\home\partimag\** folder in the USB drive.

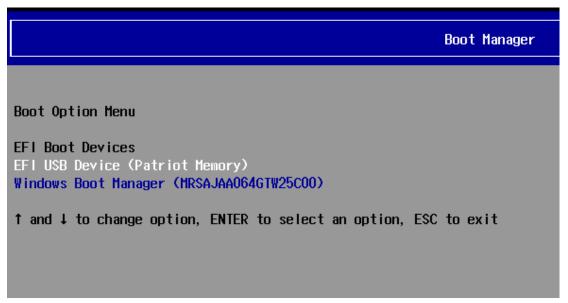


## **Booting From the USB Disk**

- 1. Turn on the computer and press F2 when you hear the beep sound to enter the BIOS setup menu.
- 2. Select **Boot Manager** and press **Enter** to continue.



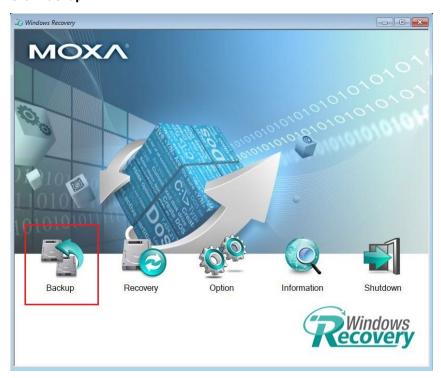
3. Select the **EFI USB Device** on the computer and press **Enter** to continue to boot from the USB device.



# **System Image Backup**

To back up the image from the USB disk, run **Windows Preinstallation Environment(WinPE)** and the **Windows Recovery** utility will display. Follow these steps.

1. Click Backup.



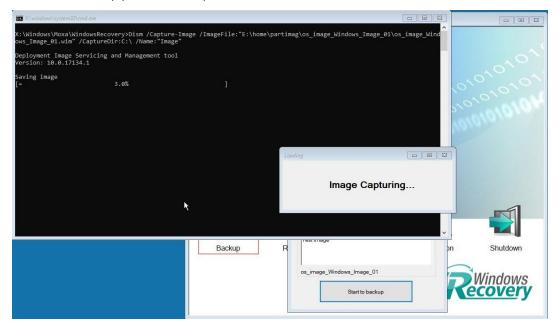
2. Select the **Source disk** to backup and **Destination USB** to store the OS image, also give an image name and description. Click **Start to backup**.



3. Click **Yes** to continue.



4. Wait for the backup process to complete.



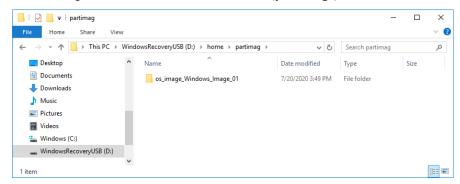
5. When the process is done, click **OK**.



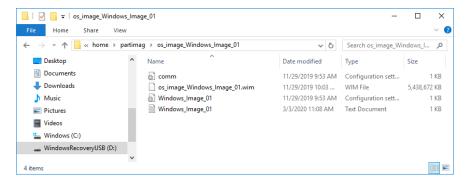
6. Click **OK**, the computer will shut down.



7. The OS image will be saved in **USB disk home\partimag\**.



8. In the os\_image folder, you can view the backup information and the image files.



# Restoring the System From a Backup

To restore the image, run the **Windows Preinstallation Environment(WinPE)** and the **Windows Recovery** utility will display. Follow these steps.

1. Click Recovery.



2. Select the **Source USB Device**, **Image Folder File** and check the image information, select the **Destination Disk** to restore. Click **Apply**.



3. If you are using Linux image, select Linux image to restore.



4. Click **Yes** to continue the process.



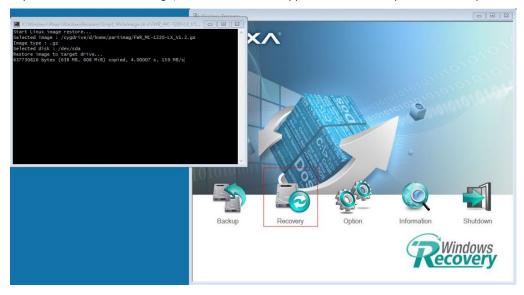
5. Click **Yes** to overwrite the destination drive.



6. Wait for the process to complete.



7. If you restore the Linux image, a new window will appear. Wait for the process to complete.



### 8. Click **OK**.



9. Click **OK**, the system will shut down and restart.



When you restart the computer, you will need to wait about 5 minutes for the computer to go through two cycles of the reboot process. The system configuration files will be initiated during the first boot-up process. Do not turn off or shut down the computer while the system is restarting.